Specifications/Instructions

# Control Motor Model MY3000

#### General

Control Motor Model MY3000 actuates a control valve or a damper when combined with a linkage.

The following control motor types are available, classified by control method:

- (1) The control motor with built-in nominal 135  $\Omega$  feedback potentiometer exerting proportional control when combined with a digital controller (Model WY5111, etc.)
- (2) Nominal 135  $\Omega$  resistance input type exerting proportional control when combined with an electric proportional controller (Models TY9000, TY991, etc.)
- (3) 4-20 mA DC input type exerting proportional control when combined with a digital controller (Model WY5111, Models R15, R35, R36, etc.)
- (4) 2-10 V DC input type exerting proportional control when combined with a digital controller (Model WY5117, etc.)
- (5) ON/OFF or floating type that exerts floating control when combined with a digital controller (Model WY7207, etc.)

When being combined with a control valve, this control motor is mounted with the Model Q455 valve linkage; when being combined with a damper, the control motor is installed with the Model Q605 damper linkage.

#### Features

- 1) A wide range of control input signal types are available.
- 2) The control motor features low power consumption and long service life.
- 3) The auxiliary switch is simple to install.
- 4) Valves and dampers in varied sizes can be actuated through the linkage.



# Safety Instructions -

Please read instructions carefully and use the product as specified in this manual. Be sure to keep this manual nearby for ready reference.

## **Usage Restrictions**

This product is targeted for general air conditioning. Do not use this product in a situation where human life may be affected. If this product is used in a clean room or a place where reliability or control accuracy is particularly required, please contact Yamatake's sales representatives. Yamatake Corporation will not bear any responsibility for the results produced by the operators.

| 🖌 🔸 In        | nstallation must be performed by qualified personnel in accordance with all applicable safety standards.  |
|---------------|---|
| U ca          | his product must be operated within its operating ranges specified in this manual. Failure to comply will ause equipment damages.<br>Installation must be carried out under the operating conditions specified in this manual to prevent equip- |
|               | nent damages.   |
| 9 · A         | Il wiring must comply with local codes of indoor wiring and electric installation rules.  |
|               | Iways disconnect power source and product power supply before performing any wiring to prevent equipment damages.   |
| <b>9</b> • U  | Ise crimp terminals with insulation for electric wires.   |
| О • м         | lake sure all the wires are tightly connected to prevent malfunctions.  |
|               | To not disassemble at any time except when removing the cover to wire or when replacing a part. Equip-<br>nent damages may occur.   |
| 9 · F         | or storage, do not stack too may container boxes in which products are packed.  |
| <b>D</b> • D  | Do not put any load on this product.  |
|               | his product may malfunction due to high temperature radiation. Do not install this product adjacently to steam coil or to a high-temperature water coil.  |
|               | woid an instrumentation that keeps equipment operating cycle excessively frequent so as not to shorten<br>the product operating life.   |
| <b>y</b> • w  | When this product is combined with a third-party controller, please consult with our sales representative.  |
| 9 · D         | Duty ratio of the operating time for the high-speed motor type needs to be 40 $\%$ or less.   |
| <b>()</b> • D | o not incinerate this product for waste disposal. Do not recycle all or part of this product, either.   |
| <b>0</b> • D  | Dispose of the product as an industrial waste complying with the local regulations.   |

Trademark information:

Infilex and Neostat are trademarks of Yamatake Corporation in Japan.

# Specifications

| Item   | Specification  |  |                                     |  |  |
|--|--|--|-------------------------------------|--|--|
| Supply voltage   | 24 V AC ± 15 %, 50 Hz/60 Hz or   |  |                                     |  |  |
|  | 100 V AC to 240 V AC (85 V AC to 264 V AC), 50 Hz/60 Hz  |  |                                     |  |  |
| Power consumption  |  |  |                                     |  |  |
| (Apparent power)   |  | oprox. 9 VA when operating, 0 VA wh        |                                     |  |  |
|  |  | h-speed type): Approx. 14 VA when          |                                     |  |  |
|  |  | 200, MY3000V0200 (24 V AC): Appr           | ox. 9 VA when operating, 4 VA       |  |  |
|  | when stopped.  |  |                                     |  |  |
|  |  | 264 V AC): Approx. 14 W when opera         |                                     |  |  |
| Operating time   | Models MY3000D0200, MY3000E0200, MY3000F0200, MY3000G0200, MY3000V0200 (24 V AC):  |  |                                     |  |  |
|  | 69 sec $\pm$ 5 sec (50 Hz) / 58 sec $\pm$ 5  |  |                                     |  |  |
|  |  | h-speed type): 35 sec $\pm$ 3 sec (50 Hz   | z)/29 sec ± 3 sec (60 Hz)           |  |  |
| <u> </u>   | Model MY3000G9200 (85 to 264 V   |  |                                     |  |  |
| Control signal   | Nominal 135 $\Omega$ feedback potentiom  | eter [Max. applied voltage: 5 V DC]        |                                     |  |  |
|  | Nominal 135 $\Omega$ resistance input  |  |                                     |  |  |
|  | 4 mA DC to 20 mA DC input (Input   |  |                                     |  |  |
|  | 2 V DC to 10 V DC input (Input imp<br>SPDT (Floating type)   |  |                                     |  |  |
| Environmental  |  |  |                                     |  |  |
| conditions   |  | Rated operating conditions                 | Transport/storage conditions        |  |  |
|  | Ambient temperature  | -20 °C to 60 °C                            | -20 °C to 70 °C                     |  |  |
|  | Ambient humidity   | 5 %RH to 95 %RH                            | 5 %RH to 95 %RH                     |  |  |
|  | (Transport and storage conditions a  | re applicable to the control motor in p    | backage.)                           |  |  |
| Composition of major   | Case: Die-cast aluminum alloy  |  |                                     |  |  |
| components   | Cover: Glass fiber-reinforced polyca   | arbonate resin (Color: Gray)               |                                     |  |  |
|  | Bracket: Steel plate   |  |                                     |  |  |
|  | Chassis and the auxiliary chassis: C   | Glass fiber-reinforced polycarbonate r     | esin                                |  |  |
| Surface treatment  | Case: None   |  |                                     |  |  |
|  | Bracket: Electrogalvanization (Gloss   | sy chromate treatment)                     |                                     |  |  |
| Installation location  | Indoors  |  |                                     |  |  |
|  |  | the control motor must be protected        |                                     |  |  |
|  |  | rosive gases and exposed to direct su      | -                                   |  |  |
| Mounting angle   | Ranging from upright to sideways (inclined to 90°), the control motor can be installed in any angle. (See Fig.                                     |  |                                     |  |  |
|  | 3.)  |  |                                     |  |  |
| \A/inin a  | (It must be installed upright for outd   | ,  |                                     |  |  |
| Wiring   |  | e required knockout hole ( $\phi$ 22 mm) o | n either side of the control motor, |  |  |
| Enclosuro rating   | and perform wiring to the terminal b   |  |                                     |  |  |
| Enclosure rating   | Equivalent to IEC IP54 (Dust-proof and splash-proof)<br>(IEC:International Electrotechnical Commission)  |  |                                     |  |  |
| Insulation resistance  | Between terminal and case: 5 M $\Omega$ c  | ,  |                                     |  |  |
| Withstand voltage  |  |  | ack potentiamator type)             |  |  |
| willisland vollage   | Power supply voltage: 24 V AC type (Floating type, nominal 135 $\Omega$ feedback potentiometer type)<br>Between terminal and case: 500 V AC/1 min. |  |                                     |  |  |
|  | Power supply voltage: 24 V AC type (Nominal 135 $\Omega$ resistance input type, 4-20 mA DC input type,   |  |                                     |  |  |
|  | 2 V DC to 10 V DC input type)  |  |                                     |  |  |
|  | Between terminal and case: 500 V AC/1 min.   |  |                                     |  |  |
|  | Power supply voltage: 85 V AC to 264 V AC type (4 mA DC to 20 mA DC input type)  |  |                                     |  |  |
|  | Between terminal and ca  |  |                                     |  |  |
| Motor shaft position for                                       |  | e shaft turned fully counterclockwise      |                                     |  |  |
| factory shipment   |  | ,  |                                     |  |  |
| Weight   | Approx. 3 kg   |  |                                     |  |  |
| Accessories  | Hex bolt M6 $\times$ 25 (for Model Q605 damper linkage)  |  |                                     |  |  |
| Optional equipment   |  |  |                                     |  |  |
| (Separate order  | Primary side: 100 V AC/200 V AC/220 V AC   |  |                                     |  |  |
| required) Secondary side: 23 V AC (for the rated load), 23 VA. |  |  |                                     |  |  |
| Order requirement  | Model number (Refer to the table "N  |  |                                     |  |  |
| •  | Linkage (Model Q455 valve linkage  |  |                                     |  |  |

# **Optional equipment**

| Waterproof connector  | Applicable wire dia.:   |  |  |
|-----------------------|---|--|--|
| Part No. 83104346-003 | (Required for splash-proof enclosing purpose.)                                  |  |  |
| Auxiliary switch      | 4 switches are built in.  |  |  |
| Part No. 83165271-004 | Max. applied voltage and current: 30 V DC, 3A; 250 V AC, 5 A (resistive load),  |  |  |
|                       | 3 A (inductive load)  |  |  |
|                       | Operating position: Adjustable between 5 % (fully closed) to 95 % (fully open). |  |  |
|                       | Each switch is set by the setting dial A, B, C, or D.                           |  |  |

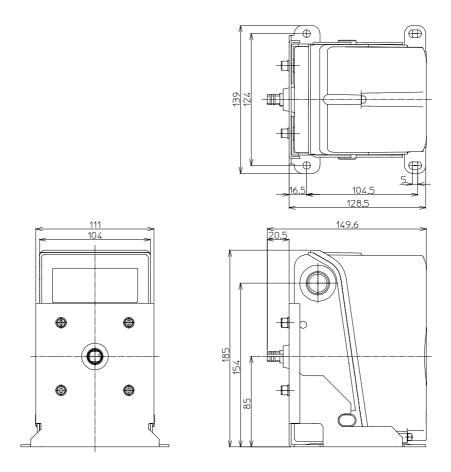
## Optional items (Separate order is required):

- 1. Model AT72-J1 power transformer Primary side: 100/200/220 V AC. Secondary side: 23 V AC, 23 VA
- 2. Model Q455 valve linkage
- 3. Model Q605 damper linkage

# **Model Number Specifications**

|              | Product specificat     |  |                   | ation     | n                  |                  |                           |                       |
|--------------|------------------------|--|-------------------|-----------|--------------------|------------------|---------------------------|-----------------------|
| Model number | Supply voltage         | Input signal                               | Angular<br>stroke |           | ing time<br>stroke | Output<br>torque | Remarks                   | Auxiliary<br>switch   |
|              | voltage                |  | SUCKE             | 50 Hz     | 60 Hz              | loique           |                           | Switch                |
| MY3000D0200  | 24 V AC                | SPDT floating                              |                   | 69<br>sec |                    |                  | ON/OFF<br>operation       |                       |
| MY3000E0200  | 24 V AC                | Nominal 135 $\Omega$ resistance input      |                   | 360       |                    |                  | operation                 |                       |
| MY3000F0200  | 24 V AC                | Nominal 135 Ω<br>feedback<br>potentiometer |                   |           | 58<br>sec          | 12.5<br>N∙m      |                           | Installed             |
| MY3000G0200  | 24 V AC                | 4 mA DC to<br>20 mA DC                     | 160°              |           |                    |                  |                           | as optional equipment |
| MY3000V0200  | 24 V AC                | 2 V DC to 10 V DC                          |                   |           |                    |                  |                           |                       |
| MY3000G9200  | 85 V AC to<br>264 V AC | 4 mA DC to<br>20 mA DC                     |                   | 72        | sec                |                  |                           |                       |
| MY3000F0400  | 24 V AC                | Nominal 135 Ω<br>feedback<br>potentiometer |                   | 35<br>sec | 29<br>sec          | 6 N∙m            | High-speed<br>motor type* |                       |

\*Duty ratio of operating time for high-speed motor type must be 40 % or less.





**Parts Identification** 

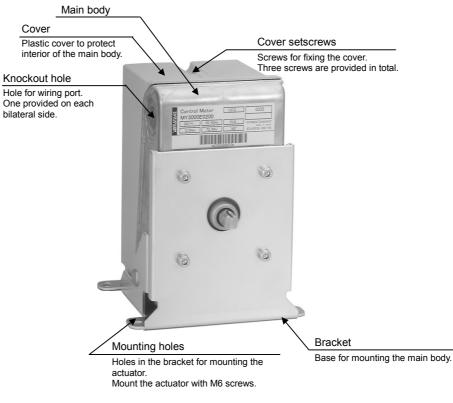


Figure 2. Parts identification

#### **Installation Precautions**

#### Atmosphere

|   | ▲ CAUTION  |
|---|--|
| 0 | <ul> <li>Avoid using the control motor in an atmosphere containing acid gases and explosive gases that may corrode the control motor components.</li> </ul>  |
| 0 | <ul> <li>Chemicals, organic solvents, and their vapors<br/>may corrode the cover. Avoid wiping the<br/>control motor with them. Do not use the<br/>control motor in an atmosphere containing<br/>chemicals or solvents.</li> </ul> |
| 0 | <ul> <li>Extreme heat may result in control motor<br/>malfunction. Do not install the control motor<br/>adjacent to steam coils, high temperature<br/>water coils, or the like.</li> </ul>   |

#### Installation

The control motor can be installed at any angle from upright to sideways based on the output shaft. However, do not mount the control motor with the output shaft pointing upward.

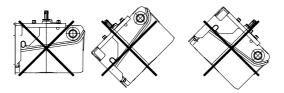


Figure 3. Incorrect mounting angles

#### When using with control valves:

If the Model MY3000 control motor is combined with a control valve (Model V5063A, V5064A, V5065A, or the like.), use the Model Q455C or Q455D valve linkage. To install the linkage, refer to AB-4051 Specifications/Instructions.

#### When using with dampers

If the Model MY3000 control motor is combined with a damper, use the Model Q605 damper linkage. To install the linkage, refer to AB-4062 Instructions/Specifications.

The crank arm to be assembled to the main shaft of the control motor comes attached to the Model Q605 damper linkage. To assemble the Model MY3000 to the damper linkage, use the M6 screws supplied with the control motor. Tighten the M6 screws with the M6 nuts supplied with the damper linkage.

#### Wiring

| 0 | • To avoid electric shock, always disconnect the power supply when performing any wiring.                |
|---|--|
| 0 | • To avoid malfunctions and accidents, never apply a voltage higher than the rated of the control motor. |
|   | • To avoid malfunctions, do not remove the cover except when wiring.                                     |

#### Wiring precautions

- Never apply a voltage higher than 5 V to the terminals
   (4), (5) and (6).
- 2) To perform wiring, a knockout hole for wiring port on the control motor must be cut out. A  $\phi$ 22 mm knockout hole is provided on each bilateral side of the terminal block. Select the knockout hole on the appropriate side, based on the mounting directions for the conduit pipe or connector, then gently knock the hole with a screwdriver. (See Fig. 2.)
- 3) For wiring, detach the cover by removing the three cover setscrews. (See Fig. 2.)
- 4) Wiring is connected to the terminals (M3.5 screws) of the control motor. Connect the wires by referring to the layout of the terminal block shown in Fig. 4, the wiring terminal diagrams shown in Figs. 10 to 14, and the examples of wiring connections shown in Figs. 15 to 18.
- 5) If the control motor is installed outdoors or in very humid environments, use the waterproof connector or the like. φ22 mm knockout holes are on bilateral sides (one for each). Select the appropriate one. (See Fig. 2.)
- 6) After wiring, replace the cover and fix with the cover setscrews. (See Fig. 2.)

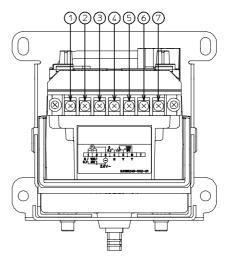


Figure 4. Layout of the terminal block with the cover removed

#### For splash-proof enclosure ...

- 1) Be sure to close the cover, inspecting that no packing or cable is caught underneath.
- 2) Waterproof the wiring port.
  - When pulling out the cable through the wiring port, use a water-proof connector Recommended product: Water-proof connector (Part No. 83104346-003)
    - water-proof connector (Part No. 83104346-003)
  - If the cable connection is made through a conduit pipe, use a water-proof plica tube or other appropriate tubes.

# Auxiliary switch (Optional)

# ▲ CAUTION

• The auxiliary switch is an optional item. It should be installed at the installation site.

2

1

 Do not apply external force on the control motor. (e.g. Placing an object on the cover.)

## Auxiliary switch

- 1. Content of package
  - Auxiliary switch unit: 1 set
  - Screws (M3 × 6):
  - Wiring label:
- 2. Specifications
- 1) Contact rating

250 V AC, 5 A (Resistive load)

- 3 A (Inductive load)
- 2) Built-in switches: 4
- 3) Terminal block

Three terminals are provided for each switch:

- ① Common terminal
- ② NO (normally open) terminal
- ③ NC (normally closed) terminal

Fig. 5 indicates the relationships between the terminals and the switches.

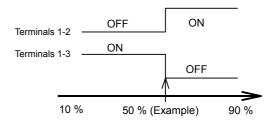
4) Switch operating position

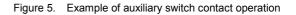
The switches operate when the arrows of the setting dials (A, B, C, and D) point at the position with  $\blacktriangleright$  marked. For setting the switches, refer to 5) and 6). Output opening range can be set from 5 to 95 %. Repeatability of operating position: Within  $\pm$  3 %. After setting, always confirm that the switches operate before the control motor is fully closed or opened.

5) Switch operating method

When the output opening outreaches the preset opening, the contact between terminals 1 and 2 makes (NO), while the contact between terminals 1 and 3 breaks (NC). (See Fig. 5.)

Fig. 5 shows a setting example of ON between the terminals 1 and 2 / OFF between the terminals 1 and 3 at 50 % opening during the opening operation.





- 6) Setting of the auxiliary switch operating position (Fig. 6 shows a setting example of the switch operating at a 50 % open position position.)
  - Set the setting dials of the auxiliary switch to the position where you want the switch to operate, by motor-driven operation. Then, using a slotted screwdriver, turn the setting dial until its arrow points at the the position with ► marked. (See Fig. 6.)
  - (2) Operate (open and close) the control motor several times near the preset position to confirm that the switch works normally.

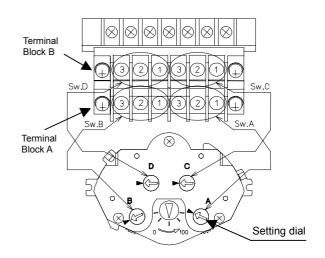
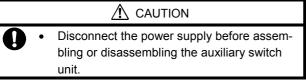


Figure 6. Setting example of the auxiliary switch with its position set to 50 %

#### 3. Assembling/disassembling the auxiliary switch



- Assembling the switch unit (See Figs. 7 and 8.)
  - (1) Break the parts A (of the chassis) and B (of the auxiliary chassis).

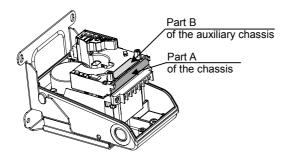
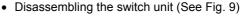


Figure 7. Parts to be removed for mounting the auxiliary switch

- (2) Insert the shaft of the auxiliary switch unit into the shaft of the control motor. (Align the tip of the arrow to the graduation side.) <Step 1 in Fig. 8>
- (3) Turn the auxiliary switch unit counterclockwise until it clicks. <Step 2 in Fig. 8>
- (4) Align the holes of the fixtures of the terminal block with the screw holes on the auxiliary chassis.
   <Step 3 in Fig. 8>
- (5) Fix the terminal block with the two screws. <Step 4 in Fig. 8>



- (1) Remove the two screws. <Step 1 in Fig. 9>
- (2) Detach the terminal block. The terminal block and fixtures are integrated in one unit. <Step 2 in Fig. 9>
- (3) Turn the auxiliary switch unit clockwise <Step 4 in</li>
   Fig. 9> while pressing the button <Step 3 in Fig.</li>
   9>.
- (4) Lift and remove the unit. <Step 5 in Fig. 9>

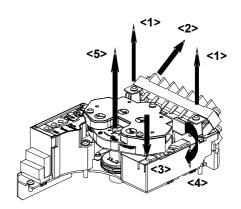


Figure 9. Disassembling the auxiliary switch unit

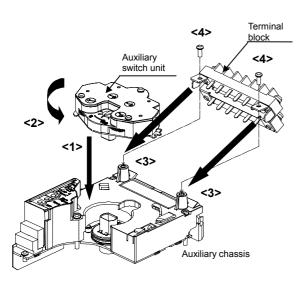
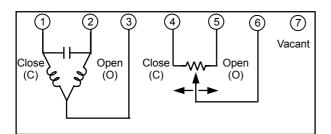


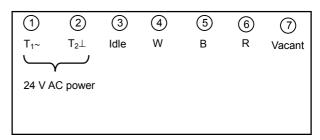
Figure 8. Assembling the auxiliary switch unit

# Wiring Terminals



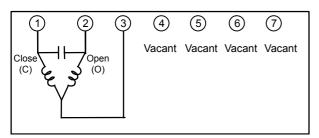
Model MY3000F

% Figure 10. Wiring terminal diagram (Model MY3000F with nominal 135  $\Omega$  feedback potentiometer)

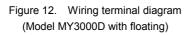


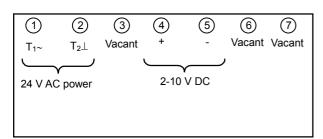
Model MY3000E

Figure 11. Wiring terminal diagram (Model MY3000E with nominal 135  $\Omega$  resistance input)



Model MY3000D

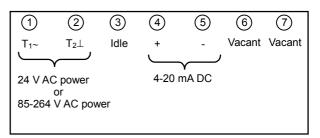




Model MY3000V

- Note: Terminals 2 (T<sub>2</sub> $\perp$ ) and 5 (-) are not connected inside of the control moter.
- Note: For common line application (one line used for 24 V AC power and 2-10 V DC input), be sure to externally connect terminals 2 and 5.

Figure 14. Wiring terminal diagram (Model MY3000V with 2-10 V DC input)



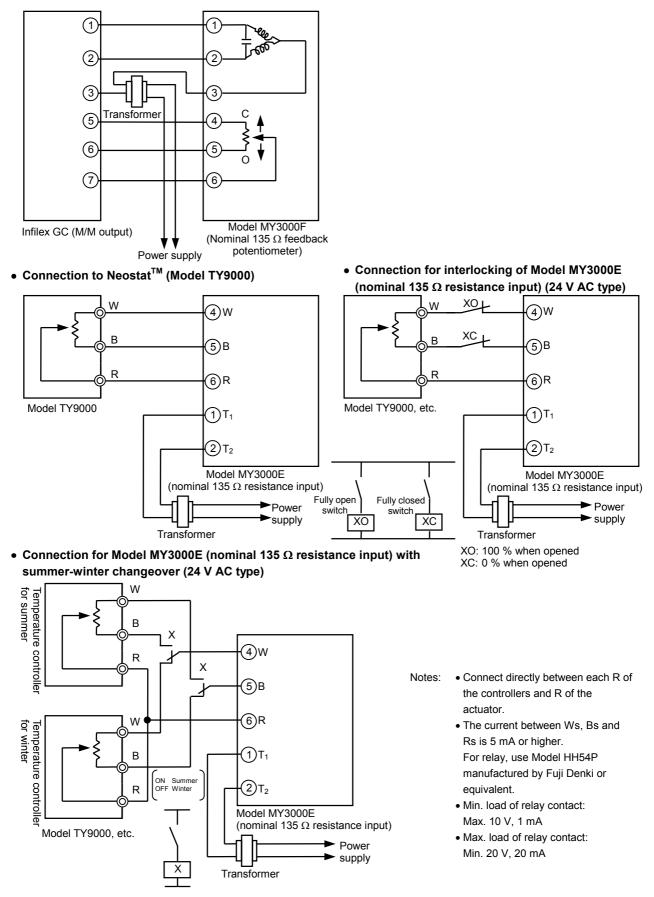
Model MY3000G

Note: Terminals 2 ( $T_2 \perp$ ) and 5 (-) are not connected inside of the control motor.

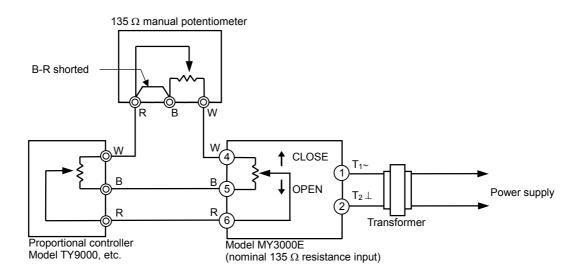
Figure 13. Wiring terminal diagram (Model MY3000G with 4-20 mA DC input)

# **Examples of Wiring Connections**

Connection to Infilex<sup>™</sup> GC

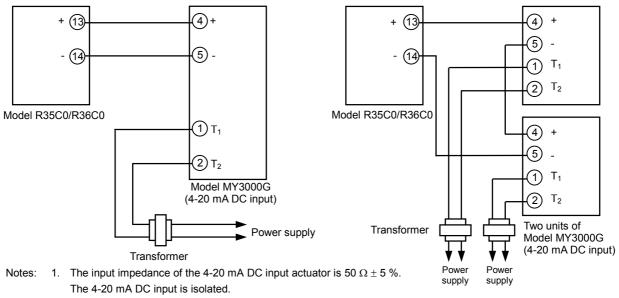






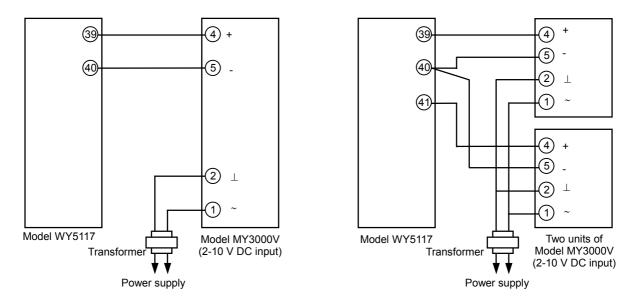
- Using a 135 Ω manual potentiometer with a proportional controller allows to set the minimum open position.
- The minimum open position can be fixed at a value within the range from 0 to approx. 100 %, depending on the value to be set.

Figure 16. Examples of wiring connections for min. open position setting (nominal 135 Ω resistance input)



2. Terminals 2  $(T_2)$  and 5 (-) are not connected inside of the actuator.

Figure 17. Examples of wiring connections to Model R35C0/R36C0



- Notes: 1. Terminals 2 (T<sub>2</sub>) and 5 (-) are not connected inside of the actuator. The input impedance of the actuator with 2-10 V DC input is 1 M $\Omega$  or higher.
  - 2. Avoid parallel wiring that passes through the power supply terminal of the actuator.



# **Maintenance and Inspections**

#### 1) Maintenance

Inspect the control motor according to Table 1.

#### 2) Maintenence

Visually inspect the control motor operations every six months or so. If you observe any of the problems indicated in Table 2, take the corresponding actions indicated below.

#### Table 1. Inspection items and details

| Inspection item    | Inspection interval | Inspection detail                                |  |
|--------------------|---------------------|--|--|
| Visual inspection  | Semiannual          | Loosened bolts                                   |  |
|                    |                     | <ul> <li>Actuator damages</li> </ul>             |  |
| Operating status   | Semiannual          | Unstable operation                               |  |
|                    |                     | <ul> <li>Abnormal noise or viblration</li> </ul> |  |
| Routine inspection | Any time            | <ul> <li>Abnormal noise or vibration</li> </ul>  |  |
|                    |                     | Unstable operation                               |  |
|                    |                     | Hunting  |  |

\* If the control motor has been inactive for an extended period of time after installation, operate (open and close) the control motor once or twice before using it.

# Table 2. Troubleshooting

(If the actions indicated below do not resolve your problem, please consult Yamatake's service personnel.)

| Problem  | Part to Check   | Action  |
|--|---|---|
| <ul> <li>The control motor does not<br/>operate.</li> </ul>                                | Wiring condition /<br>Disconnected wires  | Check the wiring.   |
| <ul> <li>The control motor stops<br/>halfway.</li> </ul>                                   | Loosened terminal connection  | Tighten the terminals.  |
| The auxiliary switch does not operate.   | Auxiliary switch (cam switch)<br>condition<br>Wiring condition /<br>Disconnected wires                    | Redo the cam switch setting.<br>Check the wiring.   |
| <ul> <li>Control sensitivity is<br/>degraded.<br/>Actuator torque is decreased.</li> </ul> | Wiring condition /<br>Disconnected wires<br>Loosened terminal connection<br>Actuator power supply voltage | Check the wiring.<br>Tighten the terminal.<br>Adjust the supply voltage (except 85 to 264 V power<br>supply types). |

Specifications are subject to change without notice.

# Yamatake Corporation Building Systems Company

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Rev.1.2 Jun. 2005 (J: Al-6387 Rev.1.2)

# **ΥΖΙΜΔΤΔΚΕ**